



Raspberry Pi Hardware Interfacing

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Raspberry Jam

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REV -



Introduction

- ▶ Who am I ?
 - ▶ Electrical engineer for a large U.S. company
 - ▶ Wide background including embedded, analog, digital, power, RF and circuit board design
 - ▶ Novice Raspberry Pi user, experienced Arduino user, 20 years experience using 8051, PIC, ARM processor in custom applications
 - ▶ Passionate engineering hobbyist for 30+ years
- ▶ What am I doing here ?
 - ▶ Basic electrical engineering relevant to Raspberry Pi / Arduino users
 - ▶ Targeted audience is hardware novices and software centric people that want to delve into using Raspberry Pi to interface to hardware
 - ▶ Most of the techniques shown here are generic techniques that are applicable to other platforms (i.e. Arduino)
 - ▶ Show techniques that can be implemented with a limited number of very basic and inexpensive parts

Raspberry Pi I/O Pins

- ▶ Raspberry Pi 3 is based around a Broadcom BCM2837 CPU
- ▶ 40 GPIO (General Purpose Input Output) pins
 - ▶ 3.3 volt logic – Will not tolerate 5V or greater input voltages – Immediate damage will occur
 - ▶ Can source or sink up to 16mA per pin depending on how pins are configured
 - ▶ Raspberry Pi 3 was designed for ~3mA per pin for a maximum total of 120mA
 - ▶ Pins used as inputs can be configured to utilize hysteresis which is good for “sloppy” input signals to reduce chatter
 - ▶ Input pins can utilize built in “pull up / down” resistors
 - ▶ Good for reading switches and keypads
 - ▶ Saves additional resistors that would normally be required
 - ▶ I/O pins are not intended to drive substantial loads directly

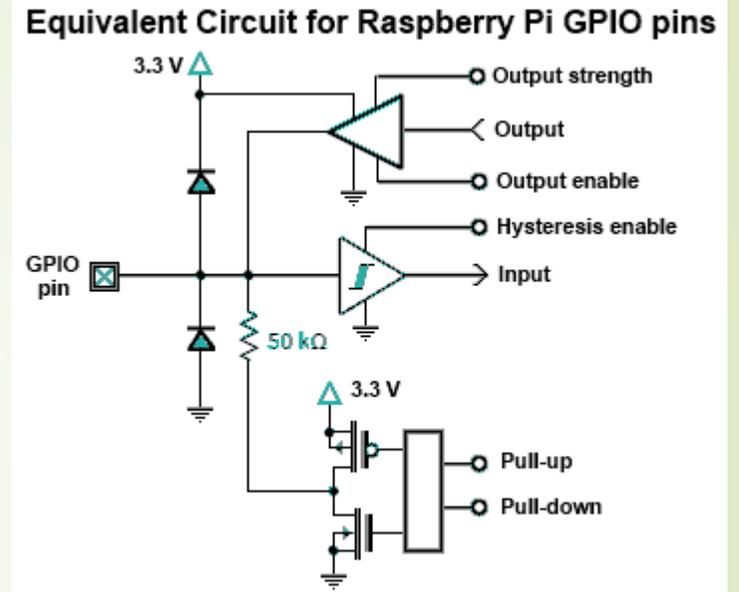


Image Source

<http://www.mosaic-industries.com/embedded-systems/microcontroller-projects/raspberry-pi/gpio-pin-electrical-specifications>

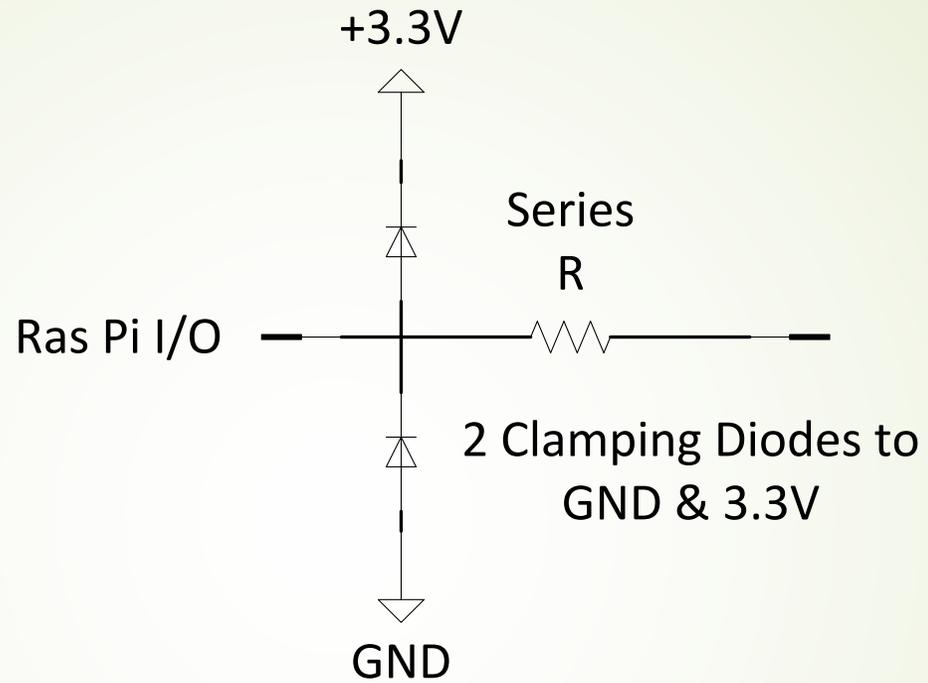
Good Links:

<http://www.mosaic-industries.com/embedded-systems/microcontroller-projects/raspberry-pi/gpio-pin-electrical-specifications>

<https://www.scribd.com/doc/101830961/GPIO-Pads-Control2>

Don't Scorch Your Pi !

- ▶ Raspberry Pi and many other electronics are quite susceptible to damage by static electricity (ESD).
 - ▶ Invest in an ESD mat and wrist strap – weakly conductive but enough to drain off static electricity. *This is especially important in the winter when humidity is low !*
 - ▶ *You must ground the mat and strap properly for it to work !*
- ▶ If your application can tolerate it, putting a resistor in series with an I/O pin is simple protection against over current damage caused by shorting I/O's to ground or 3.3V
 - ▶ $R = V/I$ so to limit current to say 10mA, $R = 3.3V / 0.01A = 330$ ohms
 - ▶ Somewhere between 1k and 10k ohms is a good choice if there is little current draw
- ▶ TVS diodes (Transorb) or MOV's can provide additional protection against over voltage damage, particularly when combined with series resistance
 - ▶ *May have to solder wires to surface mount device to get low voltage parts (3.3V) for TVS diodes*
 - ▶ *Can also use 2 schottky diodes such as 1N5817 between GND and +3.3*



Protecting Raspberry Pi I/O pins with series resistance and optional clamping diodes



Outputs and Power Switching

The Bipolar Transistor

▶ Bipolar Transistor – 2 Simple Rules

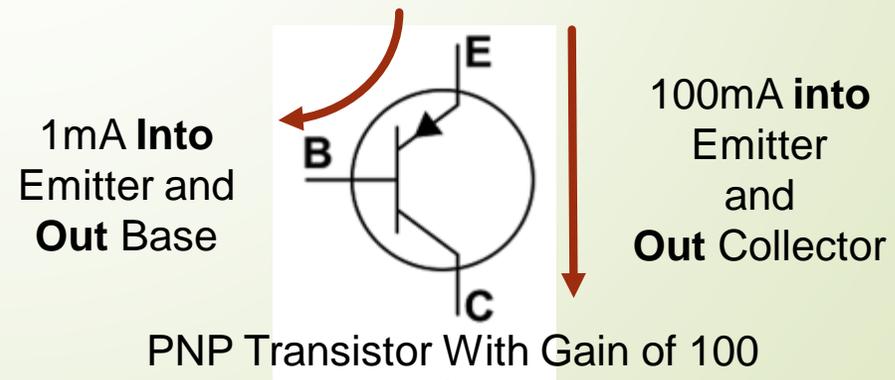
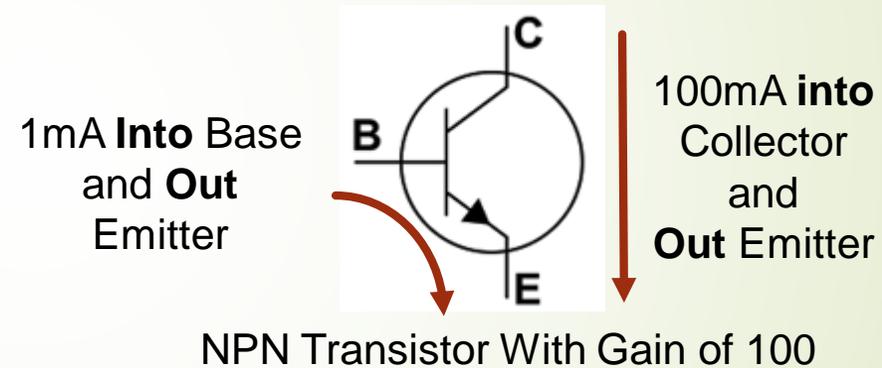
- ▶ A tiny current flowing between the base and the emitter causes a MUCH larger current to flow between the collector and the emitter. Typical current gain is ~100 – 500 for a modern small signal transistor.
- ▶ Transistor starts to turn on when voltage between base and emitter exceeds ~0.7V

▶ Transistors can be used to :

- ▶ Amplify (make bigger) voltages
- ▶ Amplify current
- ▶ Act as an on / off switch

▶ NPN vs. PNP Transistors

- ▶ “Complementary”
- ▶ Opposite Polarity



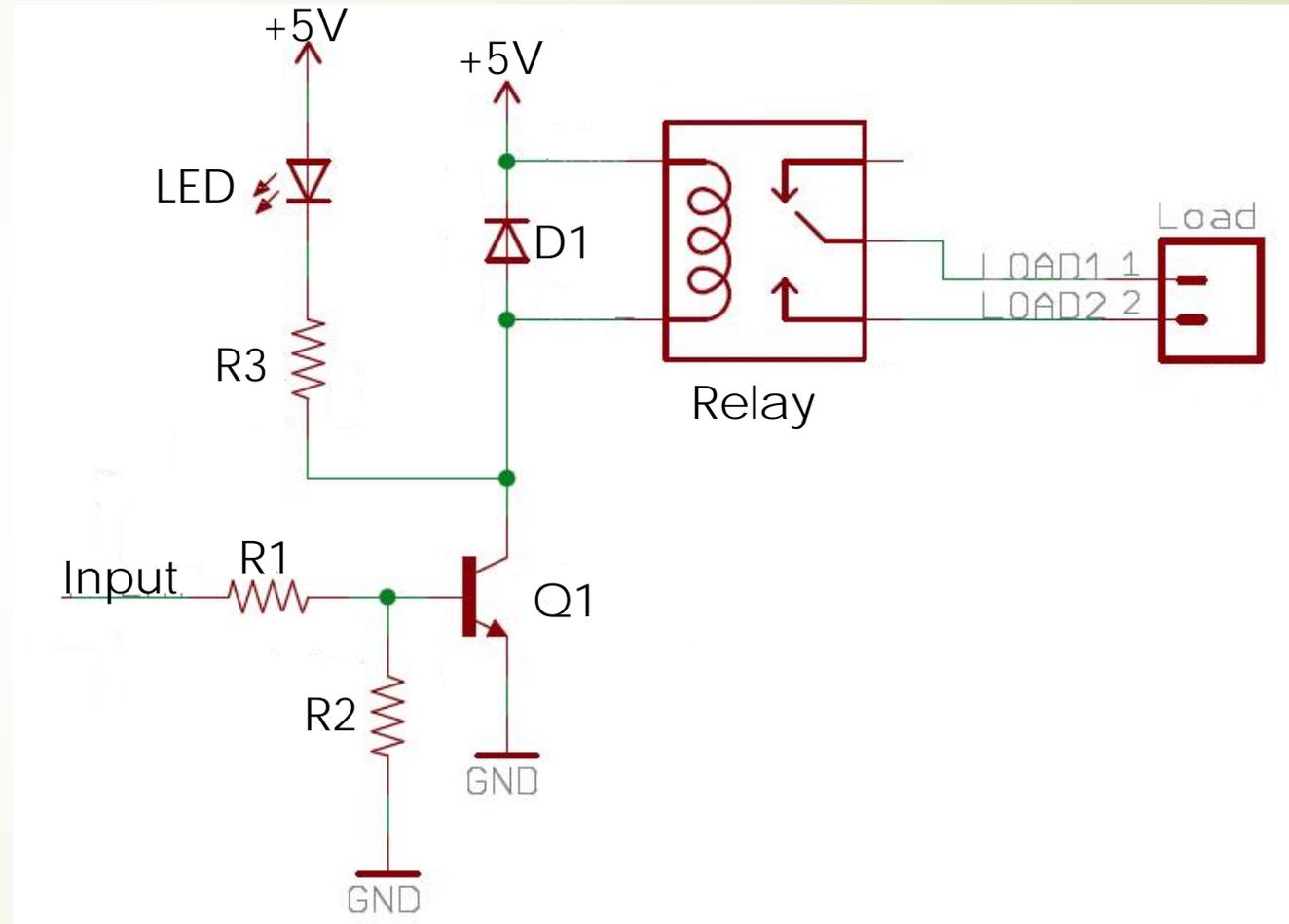


Driving Relays

- ▶ What is a Relay?
 - ▶ Relay is an electromechanical switch that uses an electromagnet to open and close a set of contacts.
 - ▶ Good for turning on big loads like motors
 - ▶ Rugged, easy to use, lots of options on contacts
 - ▶ Normally on/off contacts, multiple poles etc.
 - ▶ Electrical isolation lets us easily operate something like a 115VAC load safely
- ▶ Can't drive a relay directly with a GPIO pin; need some additional circuitry
 - ▶ Need a transistor to boost the available drive current from the GPIO pin

Driving Relays Ctd.

- ▶ Q1 is a bipolar transistor which amplifies the very small output current from the Raspberry Pi and allows it to turn the relay coil on and off
- ▶ **D1 is very important and must not be omitted !**
 - ▶ This diode safely shunts what is known as the "flyback" voltage that the coil of the relay generates when it turns off.
 - ▶ **Q1 and possibly the Raspberry Pi will be destroyed if D1 is omitted !**
- ▶ R1 is needed to limit the current into the base of Q1
- ▶ R2 is optional, but helps ensure that Q1 does not turn on accidentally if input is disconnected.
- ▶ LED and R3 are optional to show when relay is energized



Driving Relays – Circuit Design Example

- ▶ Use relay part number 8-1419125-0 made by TE Connectivity
 - ▶ Available from Digikey for \$1.35
 - ▶ 5 volt coil, 46.3 ohm resistance
 - ▶ SPST-NO (Single Position, Single Throw, Normally Open) contacts rated for 10A
 - ▶ How much current will relay coil need ? $I=V/R$ so $I=5/46.3 = 108\text{mA}$
- ▶ Use a 2N2222 bipolar transistor to switch the coil
 - ▶ Can flow 600mA between collector and emitter, rated for 40V
 - ▶ Has minimum gain of 100 with a current of 150mA
 - ▶ Want to make sure transistor is saturated as a switch, so base resistor must flow at least 1.08mA – Choose 3mA to add some margin
 - ▶ Voltage drop across base – emitter is 0.7V and GPIO voltage is 3.3V so:
 - ▶ $R=V/I = (3.3 - 0.7)/ .003 = 866.67$ ohms → Use 1k ohm resistor
- ▶ Use Red LED – Forward Voltage of 1.7V at 10mA
 - ▶ Resistor required: $R = V/I = (5V - 1.7V)/0.01 = 330$ ohms

Driving Relays – Sample Parts List

Component	Part Value	Manufacturer	Part Number	Price (Qty1)
Relay		TE Connectivity	8-1419125-0	\$1.35
Transistor (Q1)	2N2222A	Fairchild	KSP2222ABU	\$0.21
Diode (D1)	1N4148	Fairchild	1N4148	\$.10
Resistor (R1)	1k ohm, 1/8W	Stackpole	RNF18FTD1K00	\$.10
Resistor (R2)	10k ohm, 1/8W	Stackpole	RNF18FTD10K0	\$.10
LED	Red	Cree	C556D-RFE-CV0X0BB1	\$.15
Resistor (R3)	330 ohm, 1/8W	Stackpole	CF18JT330R	\$.10

All parts above available from Digikey

<http://www.digikey.com>

Solid State Relays

- ▶ Act like a relay, but with no moving parts
 - ▶ Easy to use, no moving parts, can switch very fast
 - ▶ Use transistors and other semiconductors to perform switching
 - ▶ Provide electrical isolation for safety similar to electromechanical relay
 - ▶ Can switch both AC and DC depending on model
 - ▶ Can be expensive (\$15 to \$50)
- ▶ Most of these will still need an external transistor similar to what was used for the electromechanical relay due to the input current required to actuate them



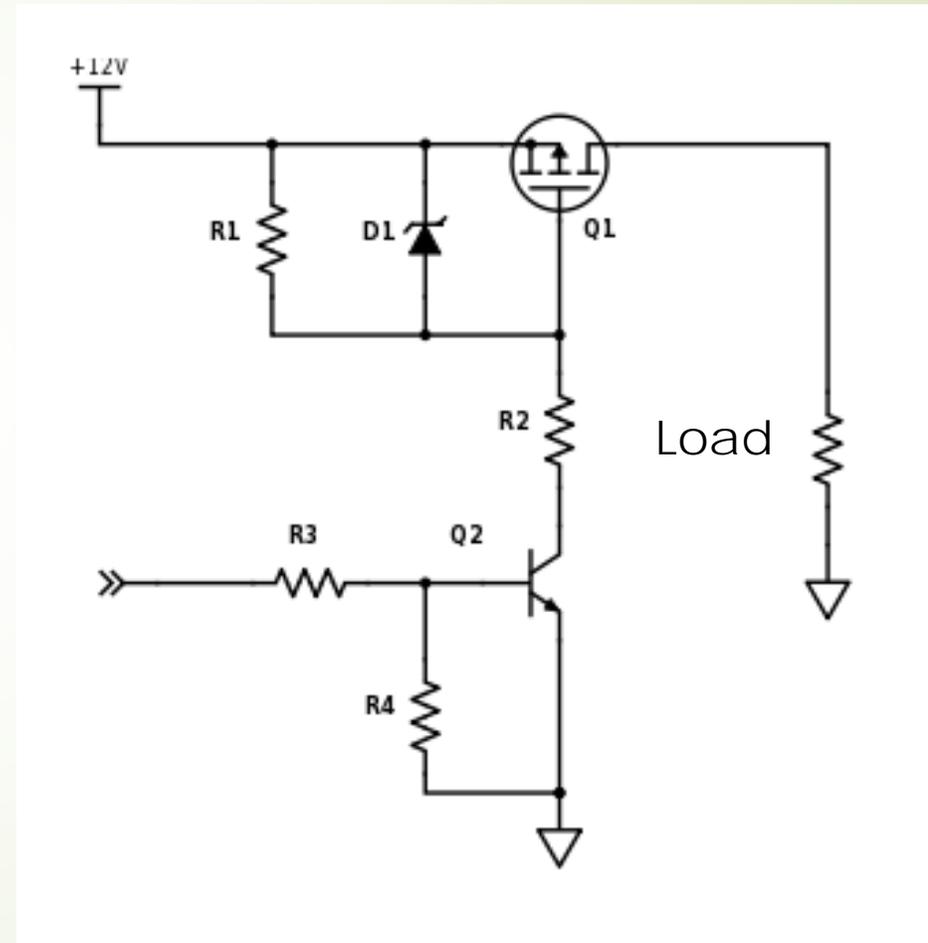


MOSFET's

- ▶ Metal Oxide Shielded Field Effect Transistor
 - ▶ Have 3 terminals (Gate Source and Drain)
 - ▶ Come in N channel and P channel types akin to NPN and PNP transistors
 - ▶ A voltage between the gate and the source controls the current flow between the source and drain
 - ▶ No current flows into the gate
 - ▶ Make excellent high current switches – Extremely low resistance when on
 - ▶ For an N-channel device, making the gate positive with respect to the source turns it on.
 - ▶ For a P-channel device, making the gate negative with respect to the source turns it on.
 - ▶ Must be cognizant of maximum gate-source voltage or part will be damaged
- 

Make Your Own Solid State Switch

- Q1 is a P-channel mosfet and is the device which will control the current through the load.
- D1 is a zener diode to protect the gate of the mosfet from overvoltage
- Q2 is an NPN transistor which "pulls" the gate of Q1 low with respect to its source
- R1 keeps Q1 off by driving the gate high when Q2 is off.
- R2 limits the current through Q2 when D1 starts to conduct.



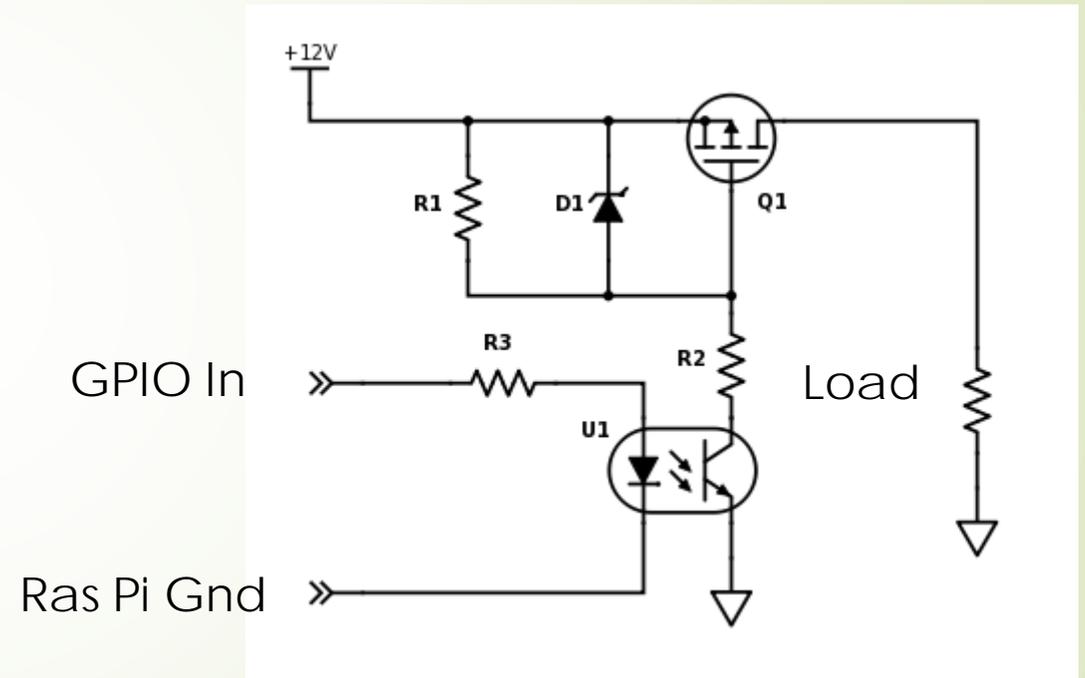
Make Your Own Solid State Switch

Component	Part Value	Manufacturer	Part Number	Price (Qty1)
MOSFET (Q1)	MOSFET P-CH 55V 74A TO- 220AB	Infineon	IRF4905PbF	\$1.80
Transistor (Q1)	TRANS NPN 40V 0.6A TO-92	Fairchild	KSP2222ABU	\$0.21
Zener Diode	15V, 1/2W	Fairchild	1N5245BTR	\$0.14
Resistor (R1,R4)	49.9k ohm, 1/8W	Stackpole	RNF18FTD49K9	\$.10
Resistor R2,R3	4.75k ohm, 1/8W	Stackpole	RNF18FTD4K75	\$.10

All parts above available from Digikey
<http://www.digikey.com>

Isolated Solid State Switch

- ▶ The simple switch previously described can be converted into an electrically isolated version by swapping Q2 for an opto-isolator as shown.
- ▶ In an opto-isolator, an LED shines light onto the base of a transistor which turns it on
 - ▶ There is no electrical connection between the input side (LED) and the output side (transistor)
 - ▶ This is a very good way to provide an extra layer of protection to a Raspberry Pi and to users.



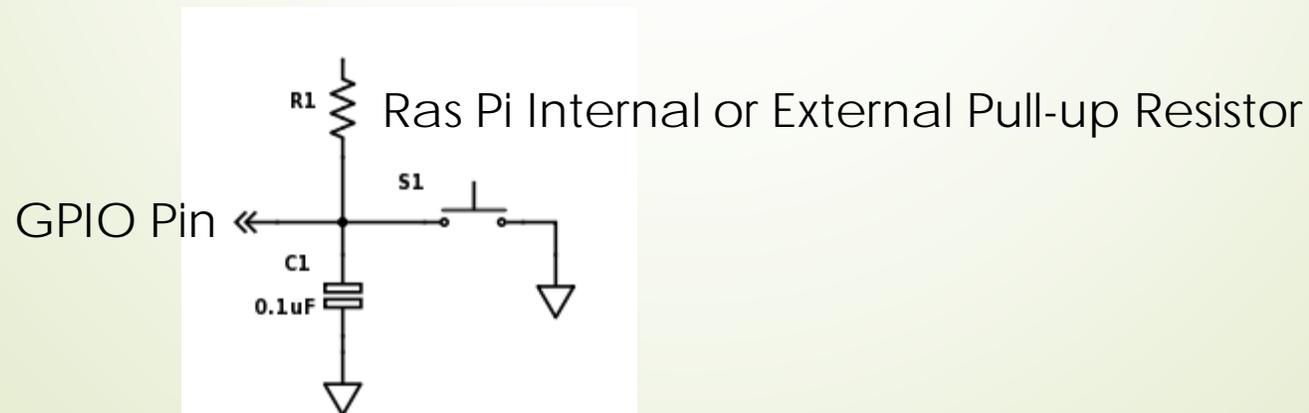
U1 could be a Lite-On LTV-816
Available at Digikey for \$0.41 ea.



Digital Inputs

Pushbuttons

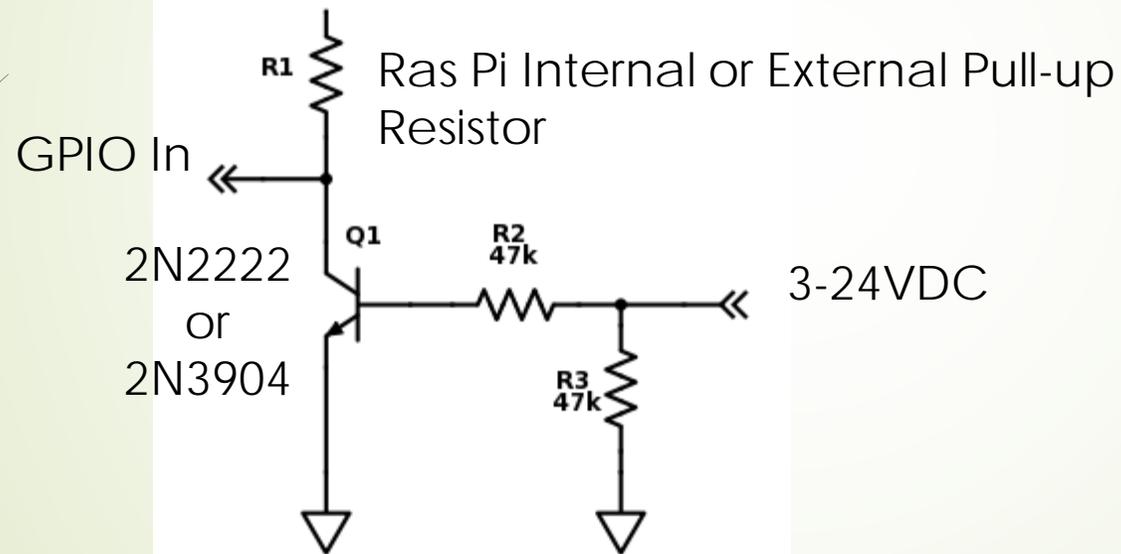
- ▶ Simple pushbuttons connected to GPIO pins
 - ▶ You can use the built in software definable pull up / down resistors, or you can use external ones connected to either the +3.3V or GND pins
 - ▶ Good idea to add a 0.1uF ceramic capacitor between the GPIO pin connected to the switch and the Raspberry Pi ground for a number of benefits
 - ▶ Mechanical switches are electrically “noisy”. The presence of the capacitor will provide a good deal of de-bouncing and avoid spurious switch reads
 - ▶ The capacitor will make the GPIO pin much less susceptible to ESD damage from a static spark from a person touching the button
 - ▶ The capacitor is a low impedance path for electromagnetic interference, and can bypass noise to ground which could otherwise be interpreted as a button press



Input Level Shifting

- Suppose you have an input signal that can be anywhere from 3 to 24VDC

Non-Isolated Wide Range Input Circuit

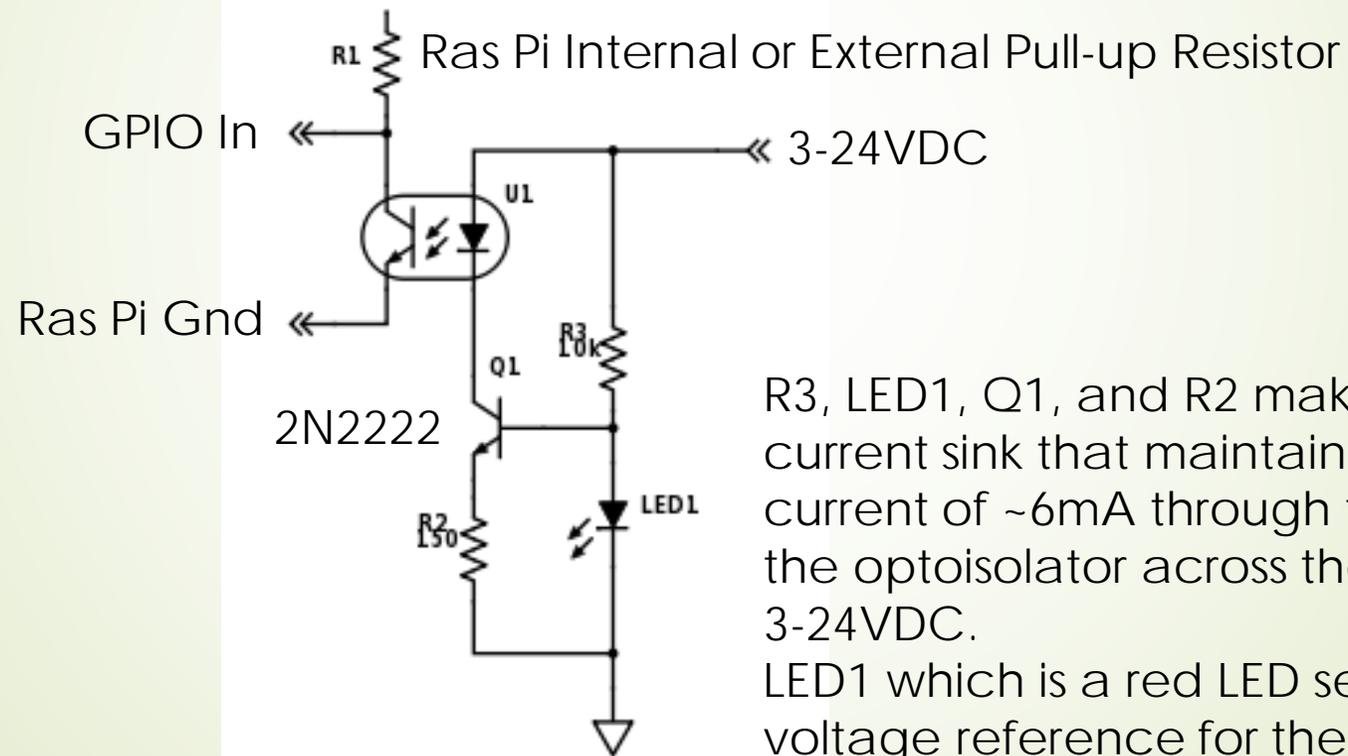


Simple NPN Switch pulls GPIO low when input goes high

Isolated Digital Inputs

- Suppose you have an input signal that can be anywhere from 3 to 24VDC
- This circuit offers electrical isolation so that there is no path through from the inputs to the Ras Pi

Isolated Wide Range Input Circuit



R3, LED1, Q1, and R2 make a constant current sink that maintains a constant current of ~6mA through the LED portion of the optoisolator across the input range of 3-24VDC.

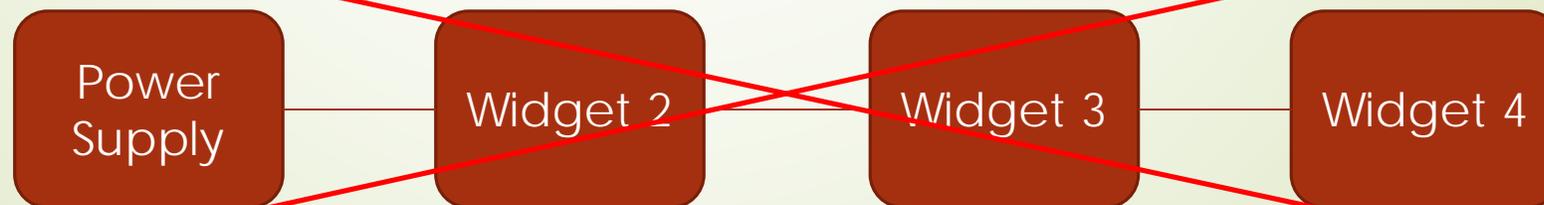
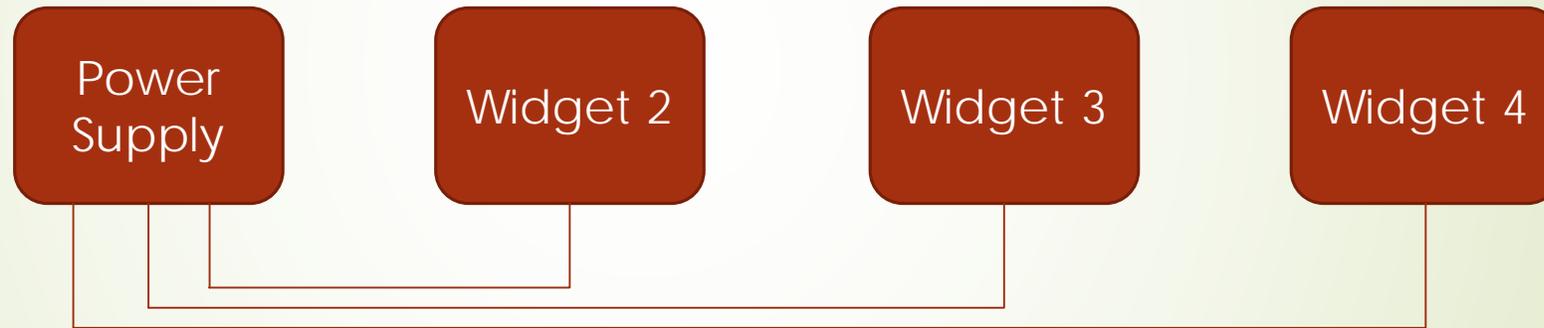
LED1 which is a red LED serves as a voltage reference for the current sink



Grounding, Signal Integrity and Electrical Noise

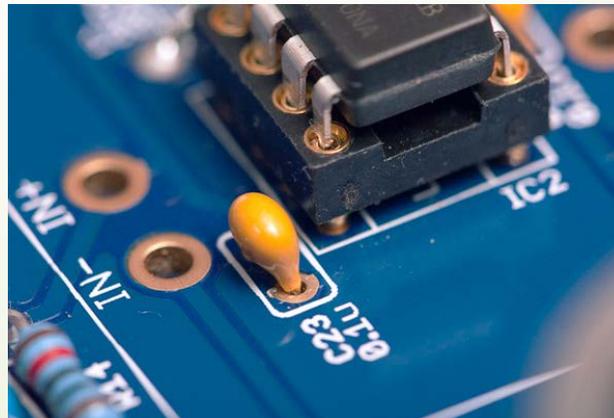
Grounding & Power Distribution

- ▶ To the greatest extent possible, try to use a single point grounding scheme when you build systems.
- ▶ Use of a poor grounding scheme in systems can lead to all kinds of issues



Bypass Capacitors

- ▶ Use bypass capacitors on sensors and IC's like A/D converters etc.
 - ▶ 0.1uF is a common value used for local decoupling capacitors on IC's
- ▶ Provides a local reservoir of charge at the sensor or IC which can combat the effects of interconnect inductance such as wires.
- ▶ Without the bypass capacitor, there can be an excessive amount of voltage ripple at the input to the device
- ▶ Many IC's and sensors will exhibit erratic behavior if decoupling capacitors are not used.
- ▶ Put the decoupling capacitor as close to the input voltage pin as possible





EMI Control / Signal Integrity

- ▶ EMI (Electro Magnetic Interference)
- ▶ Using simple twisted pairs for power distribution and routing of signals can go a long way towards controlling EMI and maintaining good signal integrity.
- ▶ Remember that when a current flows in a wire, it generates a magnetic field around the wire according to the right hand rule.
 - ▶ If we have two wires that are tightly twisted together with equal and opposite currents in them, then the magnetic fields cancel each other.
 - ▶ This prevents those fields from coupling into adjacent wires !
- ▶ By the same token, twisting signal wires together makes them much less susceptible to picking up noise by stray magnetic fields
 - ▶ A magnetic field cutting across a single separated wire can generate a voltage in it.
 - ▶ A magnetic field cutting across a twisted pair generates equal and opposite signals that cancel
- ▶ Twisted pairs are also very good for data communications like Ethernet and RS-422 because they have what is known as a characteristic impedance which allows us to avoid reflections if our circuit is designed properly.
- ▶ You can make long consistent twisted pairs with a cordless drill using a simple metal hook made from coat hanger wire !

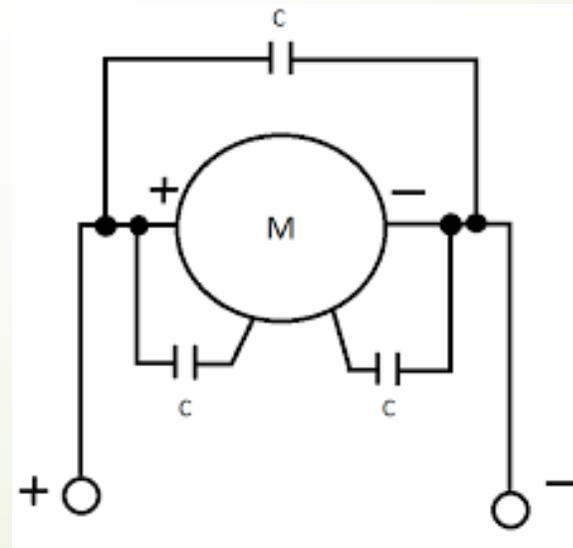
Image credits:

<https://electronics.stackexchange.com/questions/19517/why-connect-capacitors-to-motor-body>

<https://electronics.stackexchange.com/questions/239321/how-to-connect-flyback-diodes-on-a-h-bridge>

DC Motors

- ▶ Brush type DC motors can generate very large magnitude EMI spikes in the hundreds of volts which can cause all kinds of problems !
 - ▶ Arcing brushes produce broadband (kHz to hundreds of MHz) noise
 - ▶ Capacitor across terminals shunts (short circuits) differential mode noise. Capacitors to motor case shunt common mode noise.
- ▶ Need to control this problem at the motor before it has a chance to propagate
- ▶ Using a medium frequency range ferrite core with 1-3 turns of both wires through it at the motor can provide additional suppression by making it difficult for the noise to travel down the cable.
 - ▶ Laird LFB090050-000 available at Digikey for \$0.19 each



Solder a 0.1uF ceramic capacitor across the two motor terminals

Solder a 0.1uF ceramic capacitor between each motor terminal and the case



Resources

Books

- ▶ The Art of Electronics
 - ▶ Paul Horowitz & Winfield Hill
 - ▶ Best book on applied electronics ever written !
 - ▶ 3rd Edition was just published in 2016

